

Spatial point pattern models

Applied Spatial Statistics

Spatial point pattern models

Statistical models for point pattern data have many uses:

- ▶ Predicting the location of the next event
- ▶ Testing for covariate effects
- ▶ Estimating the spatial range of interactions

Spatial point pattern models

We will study models that capture all types of interactions we have discussed:

- ▶ Homogeneous Poisson process
- ▶ Inhomogeneous Poisson process
- ▶ Inhomogeneous Poisson process with covariates
- ▶ Strauss process for inhibition
- ▶ Cluster process

Poisson process

- ▶ Let $\lambda(\mathbf{s})$ be the sampling intensity at location $\mathbf{s} \in \mathcal{D}$
- ▶ The expected number of observation in $\mathcal{B} \subset \mathcal{D}$ is the volume under the intensity function

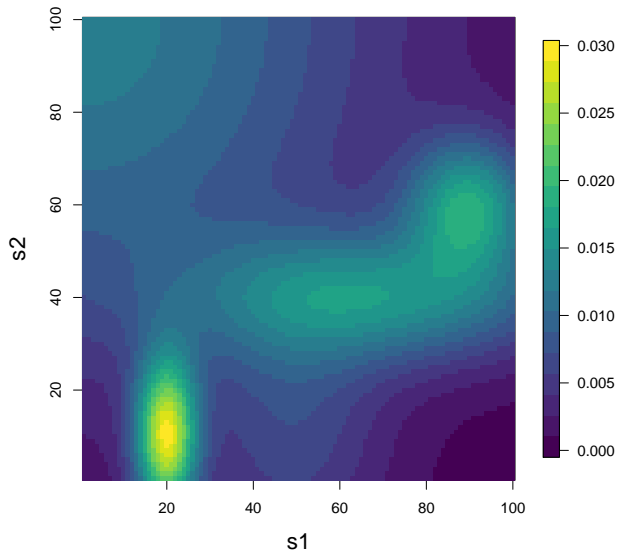
$$\lambda(\mathcal{B}) = \int_{\mathcal{B}} \lambda(\mathbf{s}) d\mathbf{s}$$

- ▶ The probability density function (PDF) is

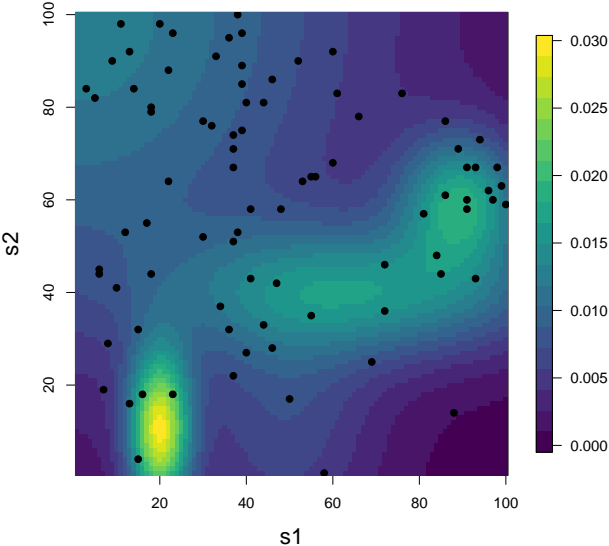
$$f(\mathbf{s}) = \frac{1}{c} \lambda(\mathbf{s})$$

where $c = \int_{\mathcal{D}} \lambda(\mathbf{s}) d\mathbf{s}$ is the normalizing constant

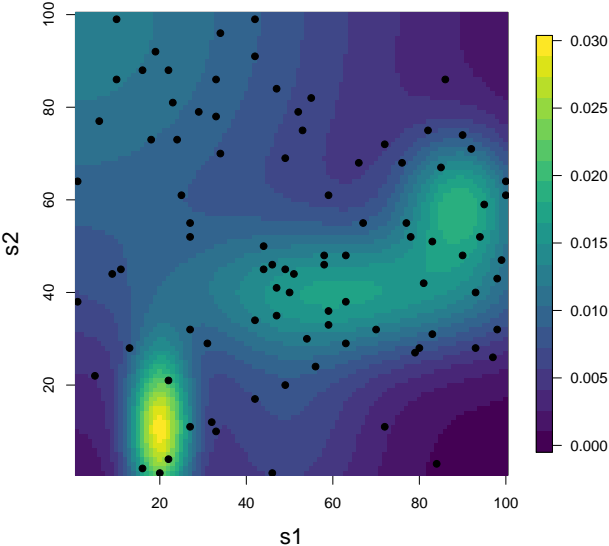
Poisson process intensity function, $\lambda(\mathbf{s})$



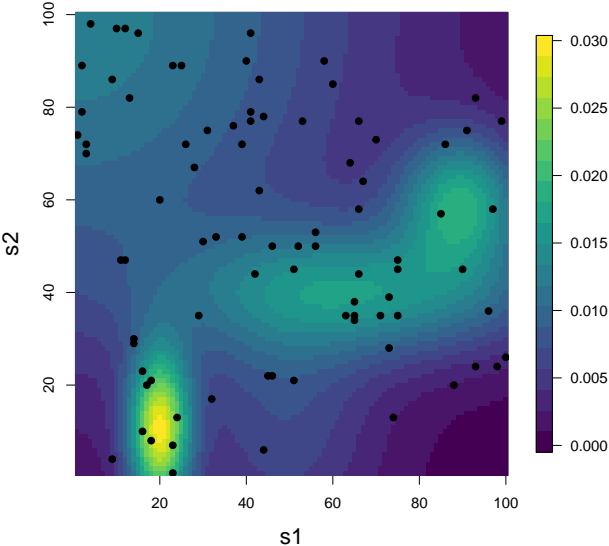
Random sample 1



Random sample 2



Random sample 3



Poisson process

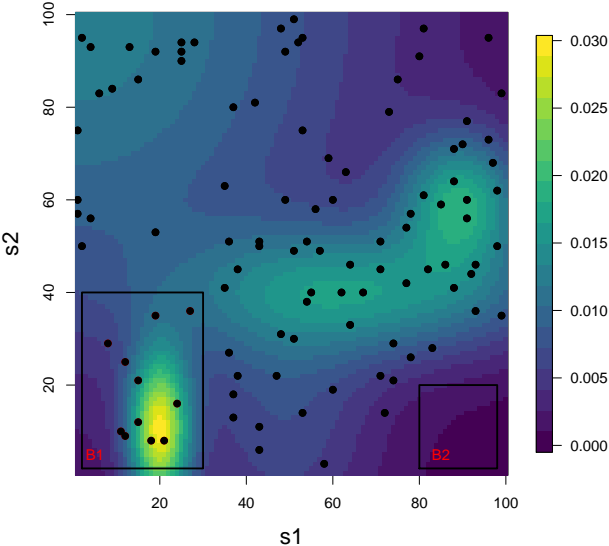
A spatial point pattern is a Poisson process with intensity function $\lambda(\mathbf{s})$ if:

1. The number of samples in \mathcal{B} , $Y(\mathcal{B})$, is distributed

$$Y(\mathcal{B}) \sim \text{Poisson}\{\lambda(\mathcal{B})\}$$

2. If \mathcal{B}_1 and \mathcal{B}_2 are disjoint, then $Y(\mathcal{B}_1)$ and $Y(\mathcal{B}_2)$ are independent

Random sample 4



Homogeneous Poisson process (HPP)

- ▶ An HPP has constant intensity, $\lambda(\mathbf{s}) = \lambda_0$
- ▶ Therefore, expected counts are proportional to area

$$\lambda(\mathcal{B}) = \int_{\mathcal{B}} \lambda(\mathbf{s}) d\mathbf{s} = |\mathcal{B}| \lambda_0$$

- ▶ The PDF is uniform,

$$f(\mathbf{s}) = \frac{\lambda(\mathbf{s})}{\int_{\mathcal{D}} \lambda(\mathbf{s}) d\mathbf{s}} = \frac{1}{|\mathcal{D}|}$$

- ▶ Therefore, HPP is completely random sampling

Homogeneous Poisson process (HPP)

Steps to sample from an HPP:

- ▶ Draw $n \sim \text{Poisson}\{\lambda(\mathcal{D})\}$ where $\lambda(\mathcal{D}) = \lambda_0|\mathcal{D}|$

- ▶ Sample $\mathbf{s}_1, \dots, \mathbf{s}_n$ uniformly and independently on \mathcal{D}

Inhomogeneous Poisson process (IPP)

- ▶ An IPP has spatially-varying intensity $\lambda(\mathbf{s})$
- ▶ The intensity function can be modeled similar to the mean function in geostatistics
- ▶ A parametric model regresses $\lambda(\mathbf{s})$ onto covariates
- ▶ A log-Gaussian Cox process assumes $\log\{\lambda(\mathbf{s})\}$ is a Gaussian process
- ▶ Kernel smoothing is nonparametric method to estimate $\lambda(\mathbf{s})$

IPP - Kernel density estimator (KDE)

- ▶ Let $\lambda(\mathbf{s}) = f(\mathbf{s})/c$ where $f(\mathbf{s})$ is the PDF and $\int_{\mathcal{D}} f(\mathbf{s})d\mathbf{s} = 1$
- ▶ Taking $c = 1/n$ gives $\hat{\lambda}(\mathcal{D}) = n$
- ▶ Any density estimator can be used to estimate p
- ▶ Simple: partition \mathcal{D} into sub-regions and use the sample proportions in each sub-region to estimate f
- ▶ KDE is a smoother version of this,

$$\hat{f}(\mathbf{s}_0) \propto \sum_{i=1}^n k(\mathbf{s}_0, \mathbf{s}_i)$$

where k is a kernel function, e.g., $k(\mathbf{s}_i, \mathbf{s}_j) = \exp(-\phi d_{ij}^2)$

Inhomogeneous Poisson process with covariates

- ▶ Assume we have p spatial covariates $X_1(\mathbf{s}), \dots, X_p(\mathbf{s})$
- ▶ Example: $X_j(\mathbf{s})$ is the latitude of \mathbf{s}
- ▶ Example: $X_j(\mathbf{s})$ is the elevation of \mathbf{s}
- ▶ Example: $X_j(\mathbf{s})$ is the distance from \mathbf{s} to the coast
- ▶ The regression model is $\log\{\lambda(\mathbf{s})\} = \beta_0 + \sum_{j=1}^p X_j(\mathbf{s})\beta_j$
- ▶ The coefficients $\boldsymbol{\beta} = (\beta_0, \dots, \beta_p)$ are interpreted just like Poisson regression

Inhomogeneous Poisson process with covariates

- ▶ The parameters can be estimated using MLE
- ▶ The conditional (given n) likelihood is

$$l(\beta) = \prod_{i=1}^n \frac{\lambda(\mathbf{s}_i; \beta)}{\int_{\mathcal{D}} \lambda(\mathbf{s}; \beta) d\mathbf{s}}$$

where $\lambda(\mathbf{s}; \beta) = \exp\{\sum_{j=1}^p X_j(\mathbf{s})\beta_j\}$

- ▶ The integral is a problem and needs to be approximated
- ▶ The likelihood requires the covariates at all locations in \mathcal{D} , not just the n sample locations

Strauss process for inhibition

- ▶ A Strauss process discourages pairs of observation to be close to each other
- ▶ Let $p_r(\mathbf{s}_1, \dots, \mathbf{s}_n)$ be the number of pair of points within r of each other
- ▶ The joint PDF of the n sample location is

$$f(\mathbf{s}_1, \dots, \mathbf{s}_n) \propto \exp\{-\beta p_r(\mathbf{s}_1, \dots, \mathbf{s}_n)\}$$

- ▶ The model (without covariates) has two parameters: interaction radius r and repulsion strength β

Strauss process for inhibition

- ▶ Estimating β and r informs us about interactions
- ▶ Example: study effects of social distancing by comparing estimates of r and β before and after COVID-19
- ▶ Hard-core Strauss process: if $\beta = \infty$ then observations within r of each other are strictly prohibited
- ▶ Soft-core Strauss process: if $\beta < \infty$ then observations within r are discouraged
- ▶ CRS: if $\beta = 0$ then observations are independent
- ▶ Parameter estimate is difficult because the likelihood has a complicated form

Cluster process

- ▶ A Poisson cluster process is a way to model attraction between events
- ▶ Below is a simple model, but there are others
- ▶ Let the parents $\mathbf{u}_1, \dots, \mathbf{u}_K$ be a sample from an HPP
- ▶ Parent k gives birth to $m_k \sim \text{Poisson}$ children
- ▶ The children of parent k are distributed as

$$\mathbf{s}_j \sim \text{Normal}(\mathbf{u}_k, \sigma^2 \mathbf{I}_2)$$