

# Analysis of Presidential Election Polling Bias

*ST 533 Final Project*

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# Introduction

The 2020 United States presidential election was the 59th quadrennial presidential election, held nominally on Tuesday, November 3, 2020. The Democratic ticket of former Vice President Joe Biden and U.S. Senator Kamala Harris defeated the Republican ticket of incumbent President Donald Trump and Vice President Mike Pence.

Presidential election polling and subsequent analysis have emerged as one of the most public applications of statistical methods. These spatiotemporal data are noisy and potentially biased. However, the presidential election pollings of 2016 and 2020 were not as accurate as they were before.

# Objective

To study the bias in state-level Presidential election polls from the elections of 2012, 2016 and 2020, including the following 3 points:

1. Devise a method to combine the individual polls to forecast the election results in each state and each year

$$X_{it} = \sum_{j=1}^{N_t} w_{itj} P_{jt}$$

2. Whether the polling bias is constant over state and election
3. What are the effects that cause bias change over state and election

# Data Description

The response:  $B_{it} = E(Y_{it} - X_{it})$

Where  $i$  represents the state,  $t$  represents the election

$Y_{it}$  is polling result over the state and election

$X_{it} = \sum_{j=1}^{N_t} w_{itj} P_{jt}$  is the average of the polls

We divided our polling data to 3 categories: Pre-Debate, Debate, Post-Debate

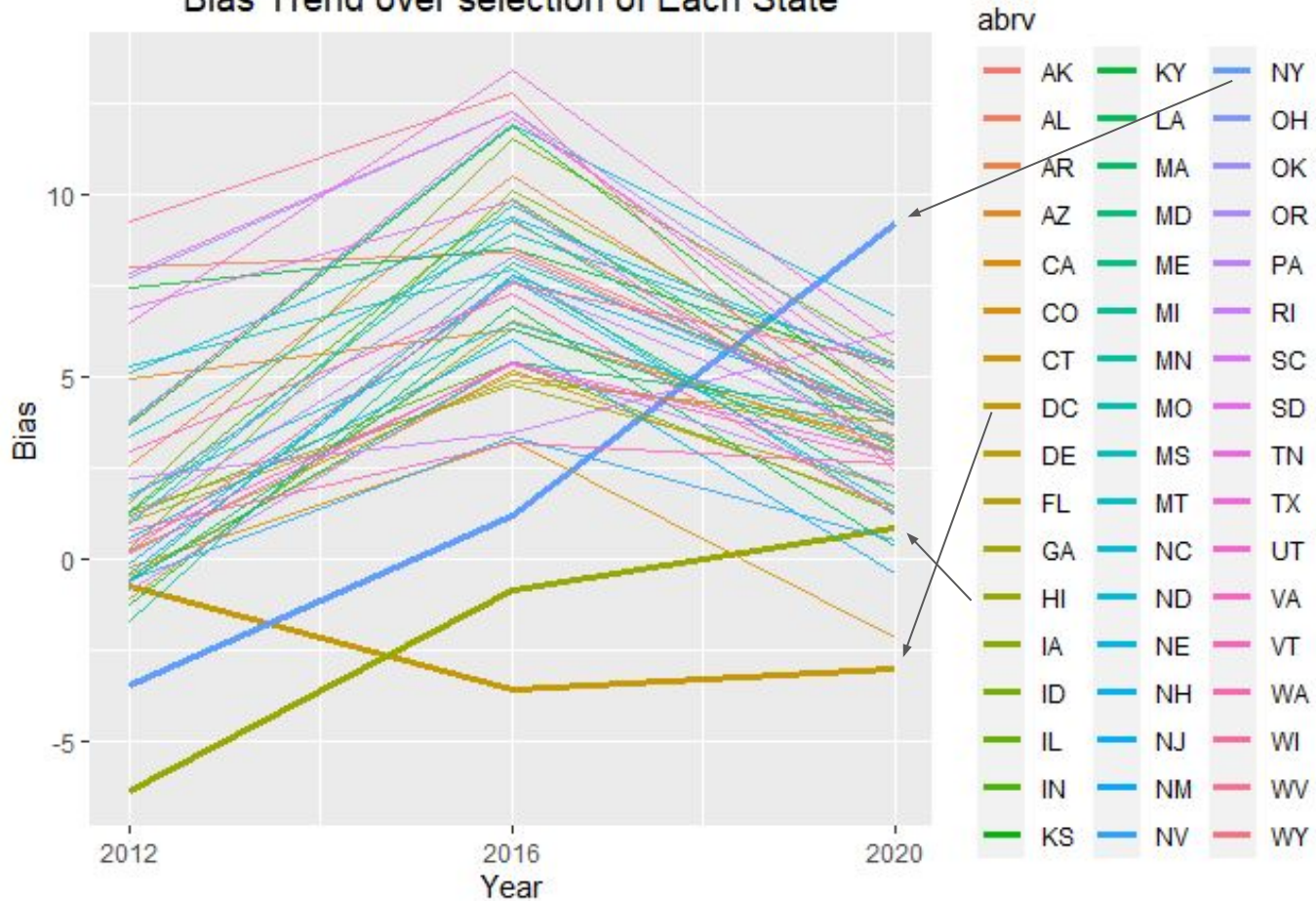
**Covariates:** Population density, Sample size/Population, Percent Republican Representatives, Percent Caucasian, # of Polling resources, Previous election results, percent agricultural land use

## Sensitivity tests for the weights

Run	Pre-D	Debate	Post-D	Mean of $ B_{it} $	Var( $B_{it}$ )
1	0.2	0.3	0.5	5.19	19.46
2	0.02	0.25	0.7	4.93	17.23
3	0	0.15	0.9	4.68	15.26
4	0	0.05	0.95	4.61	14.80
5	0	0	1	4.55	14.37

Thus, we went with run # 5 which has the lowest bias and variance

Bias Trend over selection of Each State

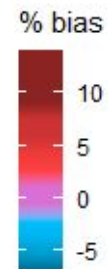
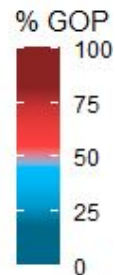
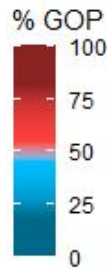


$$B_{it} = E(Y_{it} - X_{it})$$

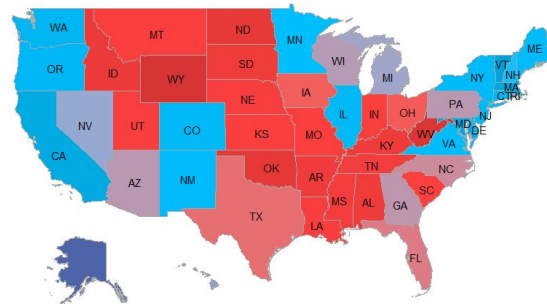
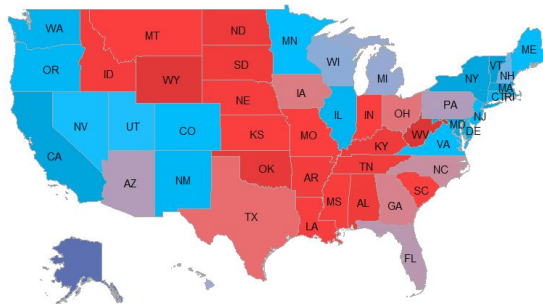
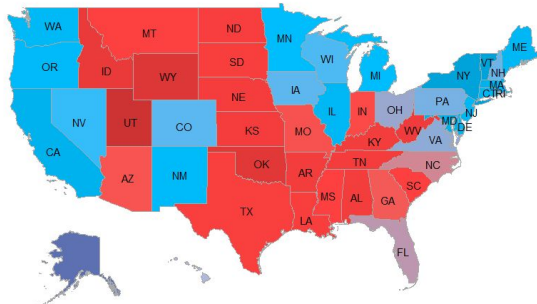
2012

2016

2020

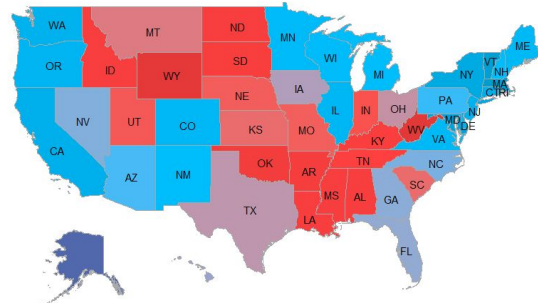
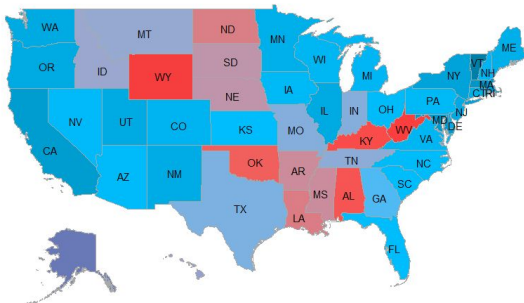
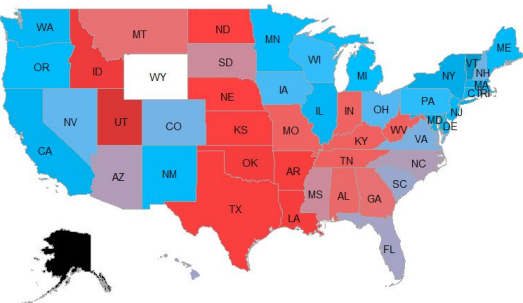


Results (Y)

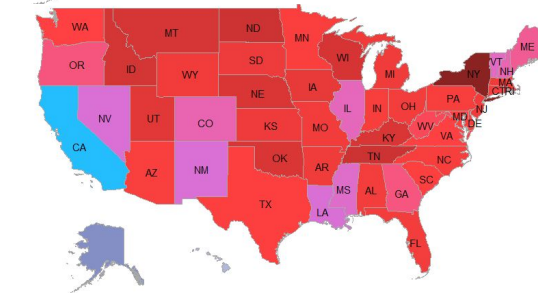
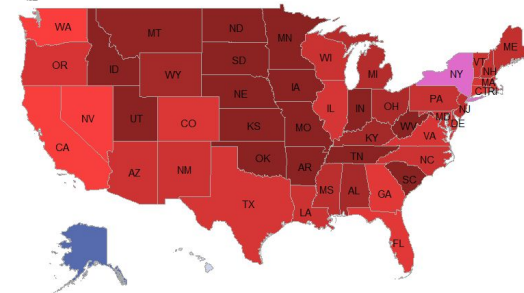
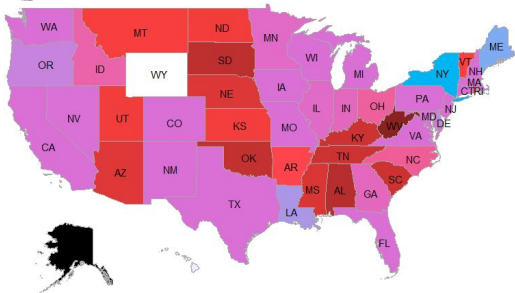


2012

Polls (X)

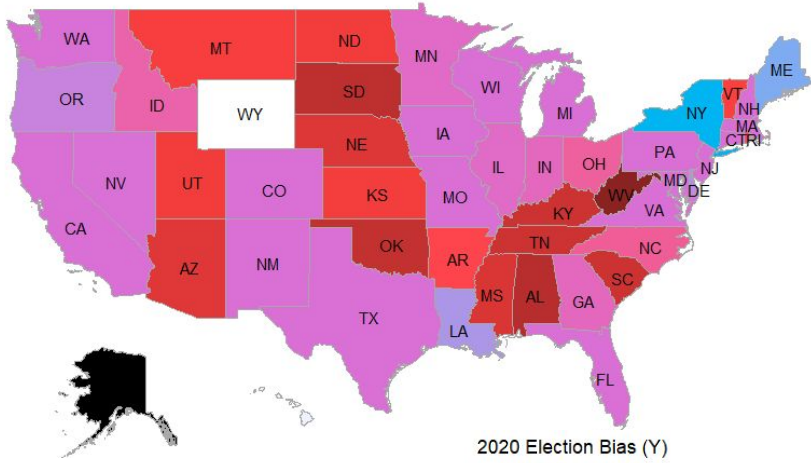


Bias (B)

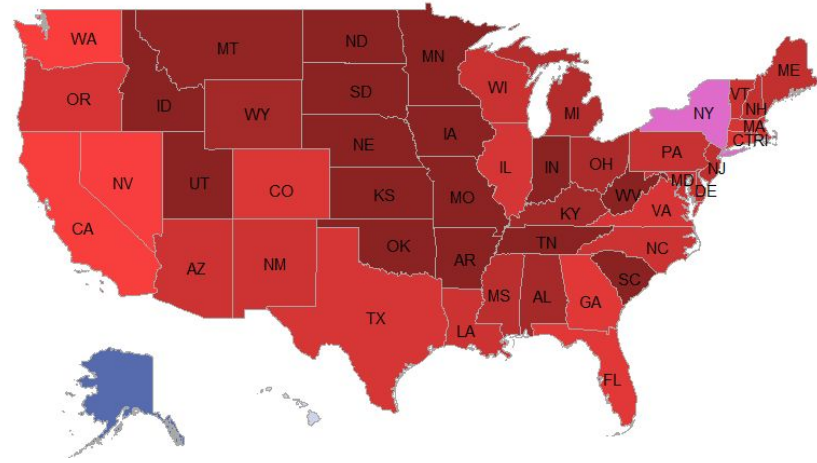


# Response Variable | Bias

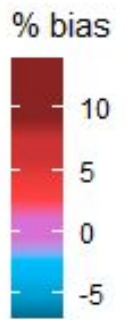
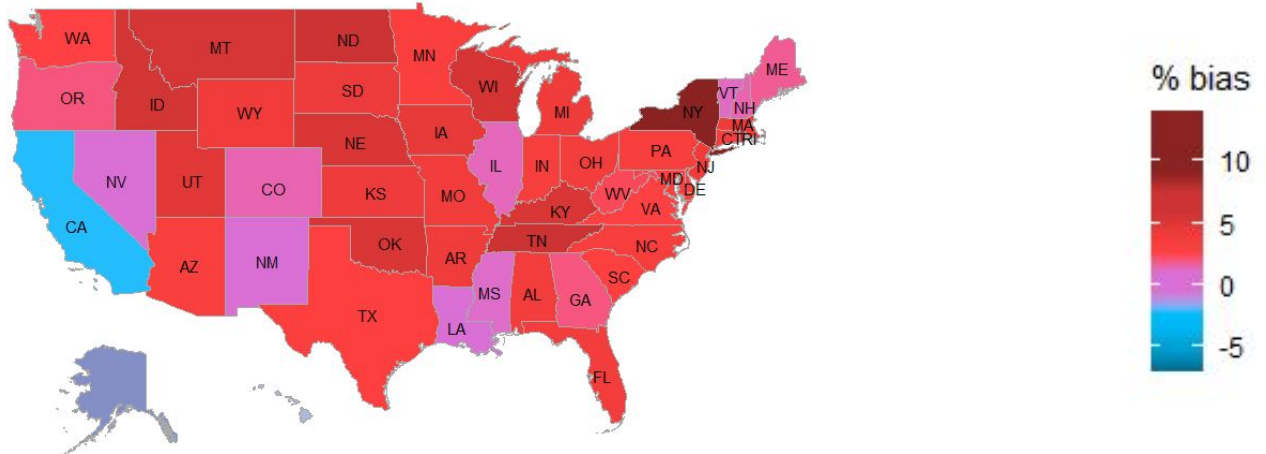
2012 Election Bias (Y)



2016 Election Bias (Y)



2020 Election Bias (Y)





# Spatiotemporal Models

R package CARBayesST: ST.CARar - AR(1)

$$\psi_{kt} = \phi_{kt},$$

$$\phi_t | \phi_{t-1} \sim N(\rho_T \phi_{t-1}, \tau^2 \mathbf{Q}(\mathbf{W}, \rho_S)^{-1}) \quad t = 2, \dots, N,$$

$$\phi_1 \sim N(\mathbf{0}, \tau^2 \mathbf{Q}(\mathbf{W}, \rho_S)^{-1}),$$

$$\tau^2 \sim \text{Inverse-Gamma}(a, b),$$

$$\rho_S, \rho_T \sim \text{Uniform}(0, 1).$$

$\rho_T$ . Temporal autoregressive parameter

$\phi_t = (\phi_{1t}, \dots, \phi_{Kt})$  Random effects for time period  $t$

$\mathbf{Q}(\mathbf{W}, \rho_S) = \rho_S[\text{diag}(\mathbf{W}\mathbf{1}) - \mathbf{W}] + (1 - \rho_S)\mathbf{I}$ , Precision matrix

# ST.CARar without Covariates

```
modelar <- ST.CARar(bias~1, family="gaussian", W=W, burnin=100000, n.sample=500000, thin=10, verbose=FALSE)
```

```

              Median    2.5%    97.5%  n.effective  Geweke.diag
(Intercept)  4.2640  4.0644  4.4623    66467.1      0.4
tau2         21.0755  5.2728  28.7437     639.9      1.0
nu2          0.0527  0.0032  4.4879     612.0     -0.9
rho.S        0.8994  0.6890  0.9923    1306.6     -1.2
rho.T        0.4520  0.2488  0.7987    1535.2     -1.2

```

MODEL	DIC	WAIC	LMPL	PROBABILITY
<b>ST.CARar</b>	<b>-97.143</b>	<b>479.584</b>	<b>-233.154</b>	<b>0.218</b>
ST.CARanova	674.637	679.035	-341.769	0.225
ST.CARlinear	798.277	797.890	-398.950	0.000

Probability of 95% interval including 0 is 0.218

# ST.CARar with Covariates

```
modelar <- ST.CARar(bias~X,family="gaussian",W=W,burnin=100000,n.sample=500000,thin=10,verbose=FALSE)
```

	Median	2.5%	97.5%	n.effective	Geweke.diag
(Intercept)	4.2051	3.8838	4.5240	40000.0	0.5
XGOPrep	0.5804	-0.2420	1.4073	28274.3	0.0
Xsampop	0.1254	-0.5745	0.8384	6193.6	-0.8
Xcaucasian	0.7078	0.1606	1.2481	17627.7	1.3
Xpolln	-0.3069	-0.7133	0.0985	33660.2	0.3
Xprevele	1.1360	0.2463	2.0291	33349.1	-0.6
Xagland	0.0675	-0.3414	0.4839	30973.0	0.4
Xpopden	-0.0594	-0.5780	0.4500	35462.9	0.5
tau2	1.1370	0.0323	5.2367	1990.9	0.6
nu2	3.7398	2.3885	5.1436	2991.2	-0.7
rho.S	0.9952	0.9550	0.9999	3153.2	-0.3
rho.T	0.1527	0.0058	0.7581	8531.4	-0.3

MODEL	DIC	WAIC	LMPL	PROBABILITY
<b>ST.CARar</b>	634.843	640.204	-322.619	0.191
<b>ST.CARanova</b>	645.664	648.848	-324.922	0.116
<b>ST.CARlinear</b>	756.494	756.065	-378.210	0.0748

# Space and Time Separately

# CAR model

R package CARBayes, S.CARLeroux function

$$\psi_k = \phi_k$$
$$\phi_k | \phi_{-k}, \mathbf{W}, \tau^2, \rho \sim N \left( \frac{\rho \sum_{i=1}^K w_{ki} \phi_i}{\rho \sum_{i=1}^K w_{ki} + 1 - \rho}, \frac{\tau^2}{\rho \sum_{i=1}^K w_{ki} + 1 - \rho} \right)$$

$$\tau^2 \sim \text{Inverse-Gamma}(a, b)$$

$$\rho \sim \text{Uniform}(0, 1).$$

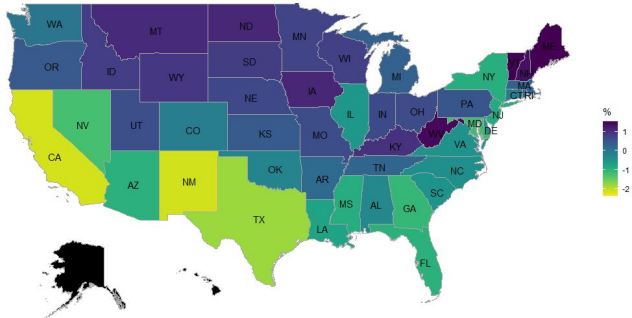
# CAR Model Results of 2012 Election Bias

```
model <- S.CARleroux(Y~X, family="gaussian", w=w, burnin=20000,n.sample=200000,thin=10,verbose=FALSE)
```

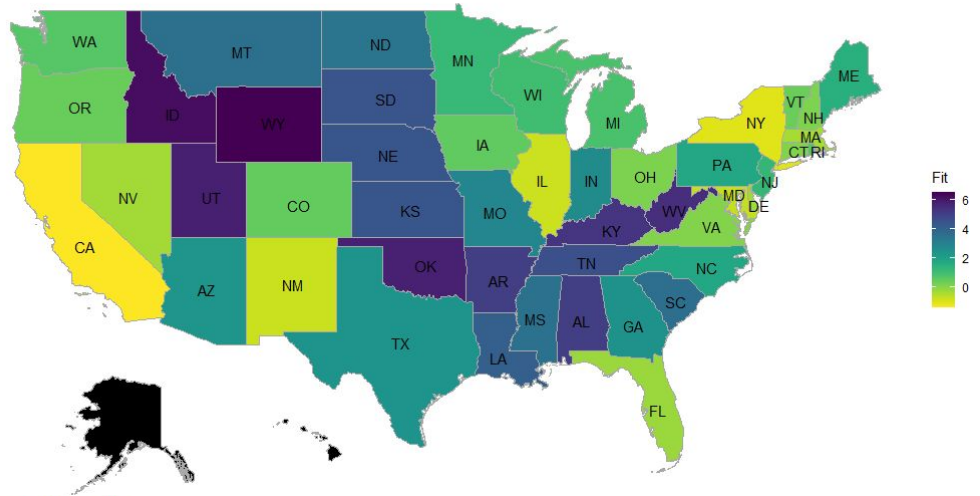
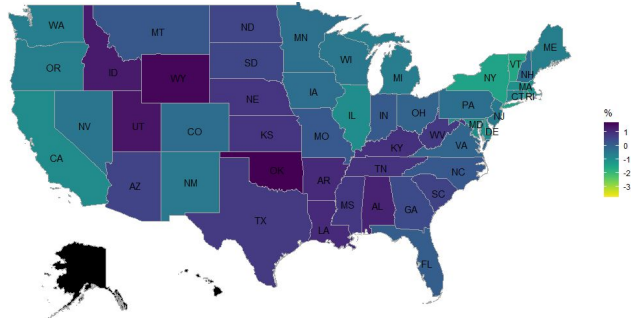
	Median	2.5%	97.5%	n.effective	Geweke.diag
(Intercept)	2.0924	1.4828	2.7014	16768.4	0.2
xpopden	0.7473	-0.2335	1.7246	18000.0	1.0
xrep	0.6172	-0.6874	1.9250	17593.3	-0.1
xsamp	-0.2897	-1.0895	0.5014	17499.4	0.6
xcaucasian	0.8113	0.0502	1.5706	17582.1	0.9
xpolln	-0.5917	-1.3867	0.1987	18000.0	0.5
xprevelc	1.5713	-0.0609	3.1607	18000.0	0.2
xagland	-0.3848	-1.1107	0.3414	18000.0	0.1
nu2	4.5457	2.9955	7.2269	16448.1	0.5
tau2	0.0083	0.0021	0.0941	1692.3	-1.3
rho	0.3623	0.0173	0.9129	8442.2	0.1

significant covariates

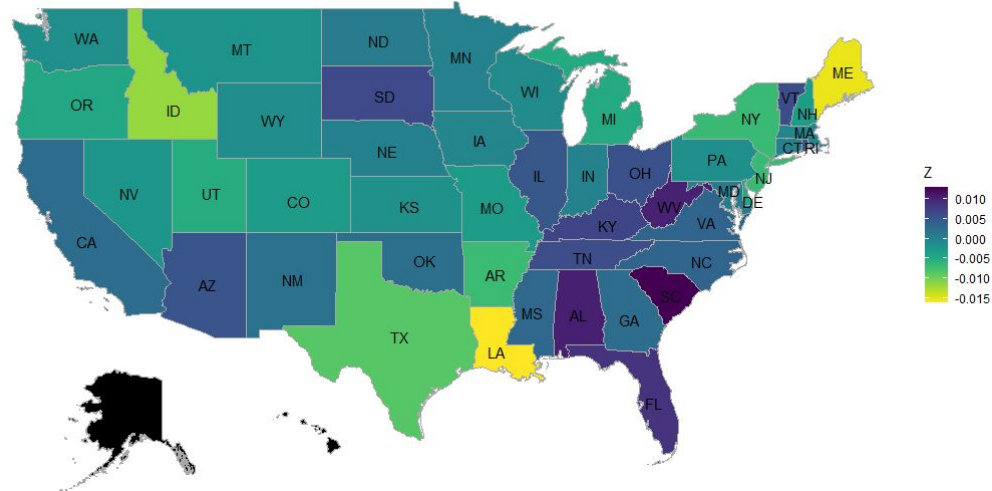
scale(% Caucasian)



scale(Prev Election % GOP)



2012 Spatial Correlation



# CAR Model Results of 2016 Election Bias

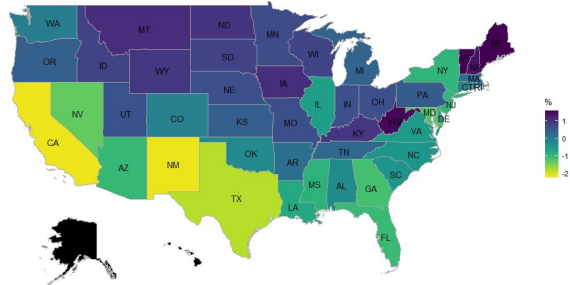
```
model <- s.CARleroux(Y~X, family="gaussian", w=w, burnin=20000,n.sample=500000,thin=10,verbose=FALSE)
```

	Median	2.5%	97.5%	n.effective	Geweke.diag
(Intercept)	7.4119	6.9551	7.8682	80000.0	0.1
XGOP_rep	0.5236	-0.5703	1.6167	80000.0	-1.1
Xsamppop	0.2518	-0.3591	0.8753	80000.0	-0.1
Xcaucasian	1.0389	0.3761	1.7087	80000.0	-0.1
Xpolln	-0.4868	-1.0431	0.0711	80000.0	-0.2
Xprevelc	1.5743	0.3596	2.7894	80000.0	1.0
Xagland	0.4465	-0.0600	0.9548	80000.0	1.2
Xpopden	-0.3320	-1.0088	0.3532	79049.2	0.0
nu2	2.4705	1.6531	3.9086	61882.5	-0.3
tau2	0.0085	0.0021	0.0943	3982.4	0.9
rho	0.3753	0.0176	0.9172	35957.9	2.5

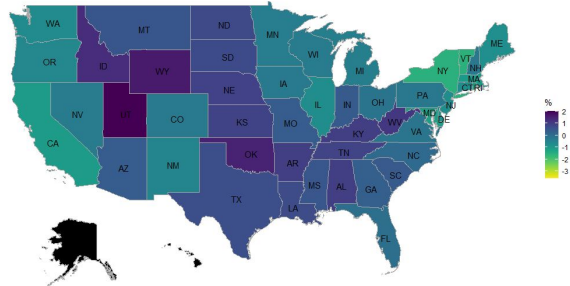


significant covariates

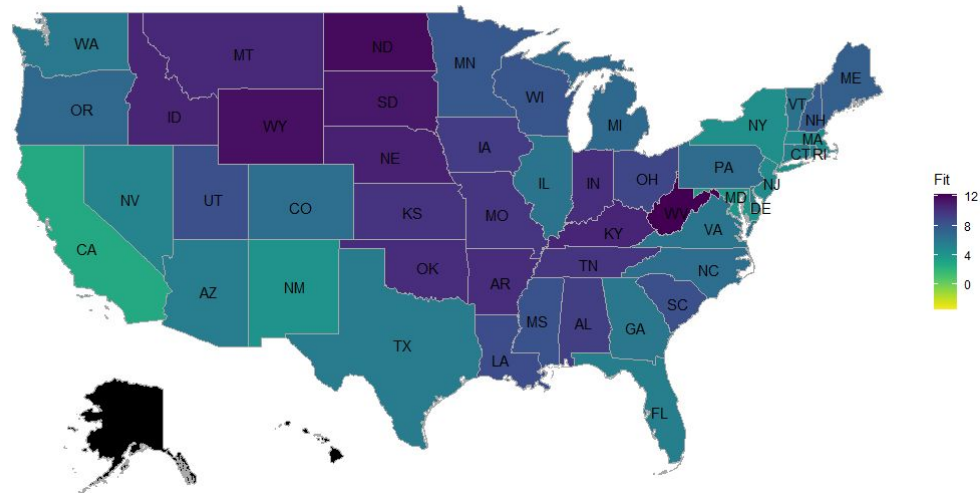
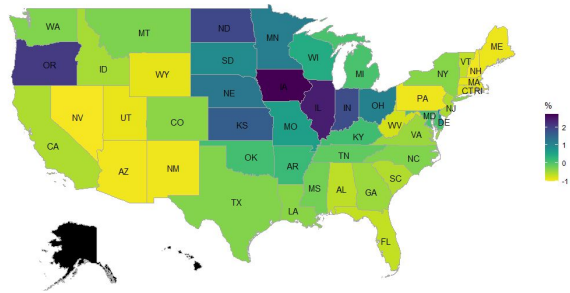
scale(% Caucasian)



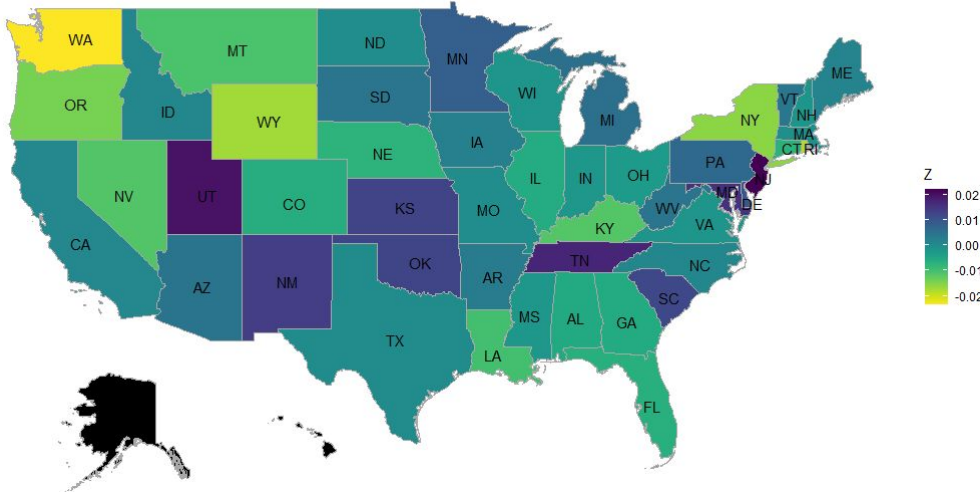
scale(Prev Election  
% GOP)



scale(% Ag Land)



2016 Spatial Correlation



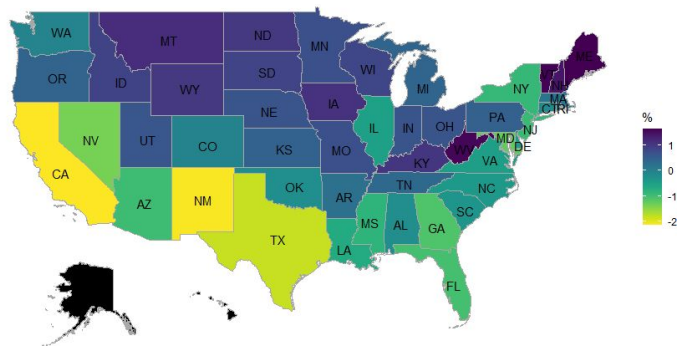
# CAR Model Results of 2020 Election Bias

```
model <- s.CARleroux(Y~X, family="gaussian", w=w, burnin=50000,n.sample=500000,thin=10,verbose=FALSE)
```

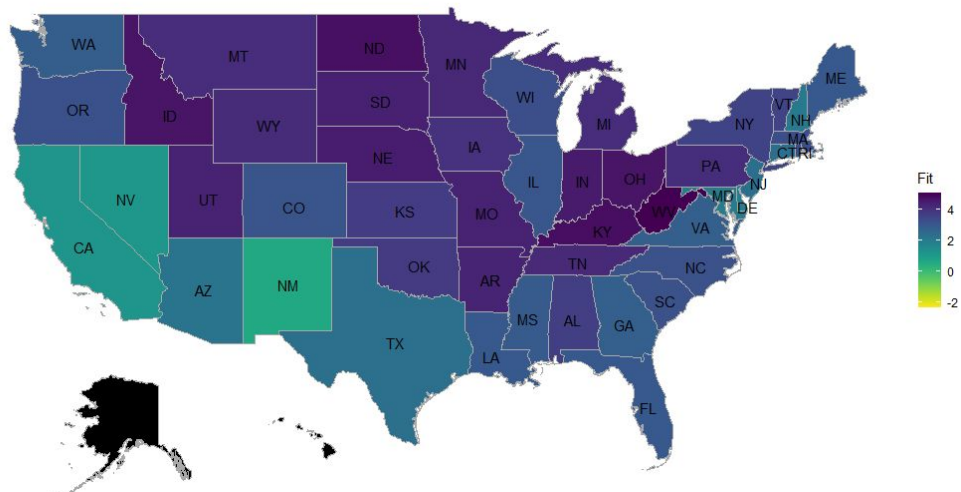
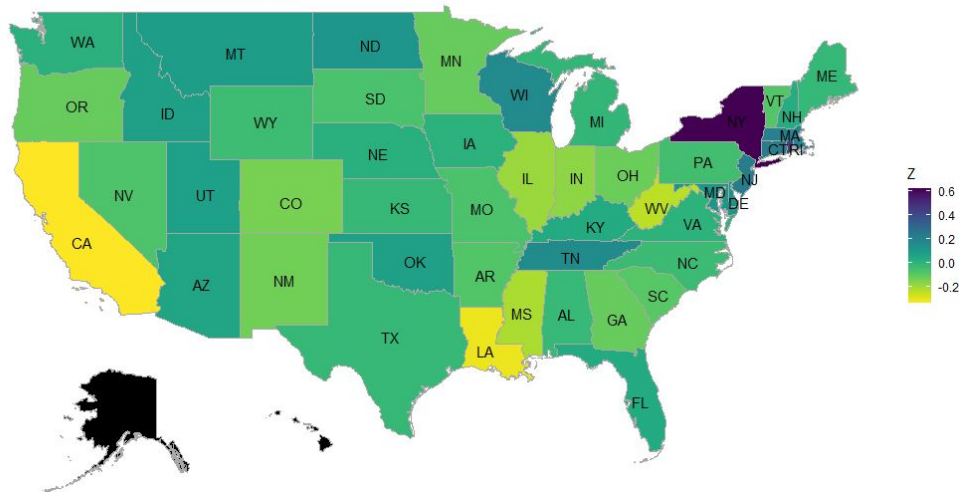
	Median	2.5%	97.5%	n.effective	Geweke.diag
(Intercept)	3.1804	2.6535	3.6970	240000.0	0.1
XGOP_rep	0.5374	-0.7008	1.8097	36555.6	-0.8
Xsampop	-0.5797	-1.2768	0.1216	65401.2	0.0
Xcaucasian	1.0638	0.2496	1.8482	36582.6	1.5
Xpolln	0.2394	-0.3536	0.8333	121677.5	0.2
Xprevelc	-0.3699	-1.8147	1.0794	130733.1	0.0
Xagland	0.0661	-0.5053	0.6373	75519.8	-2.4
Xpopden	-0.5251	-1.2862	0.2382	91995.1	0.4
nu2	3.2801	0.0252	5.2314	952.6	0.4
tau2	0.0089	0.0022	4.7329	537.7	-0.6
rho	0.3694	0.0170	0.9154	61922.4	0.6

## significant covariates

scale(% Caucasian)



2020 Spatial Correlation



# Non-spatial Linear Model

```
Call:
lm(formula = Y ~ X)

Residuals:
    Min       1Q   Median       3Q      Max
-6.7210 -2.3292 -0.5392  2.3433  7.2301

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept)  4.29057    0.25713   16.687 <2e-16 ***
Xyear         0.62745    0.46663    1.345  0.1810
Xpopden       0.10138    0.37934    0.267  0.7897
Xrep          0.47836    0.55613    0.860  0.3912
Xsamp        -0.12084    0.50416   -0.240  0.8109
Xcaucasian   0.72355    0.32276    2.242  0.0266 *
Xpolln      -0.23145    0.29580   -0.782  0.4353
Xprevelc     1.31980    0.64855    2.035  0.0438 *
Xagland      0.02641    0.28618    0.092  0.9266
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 3.106 on 137 degrees of freedom
(1 observation deleted due to missingness)
Multiple R-squared:  0.3329,    Adjusted R-squared:  0.2939
F-statistic: 8.544 on 8 and 137 DF,  p-value: 2.14e-09
```

```
Call:
lm(formula = Y ~ yr)

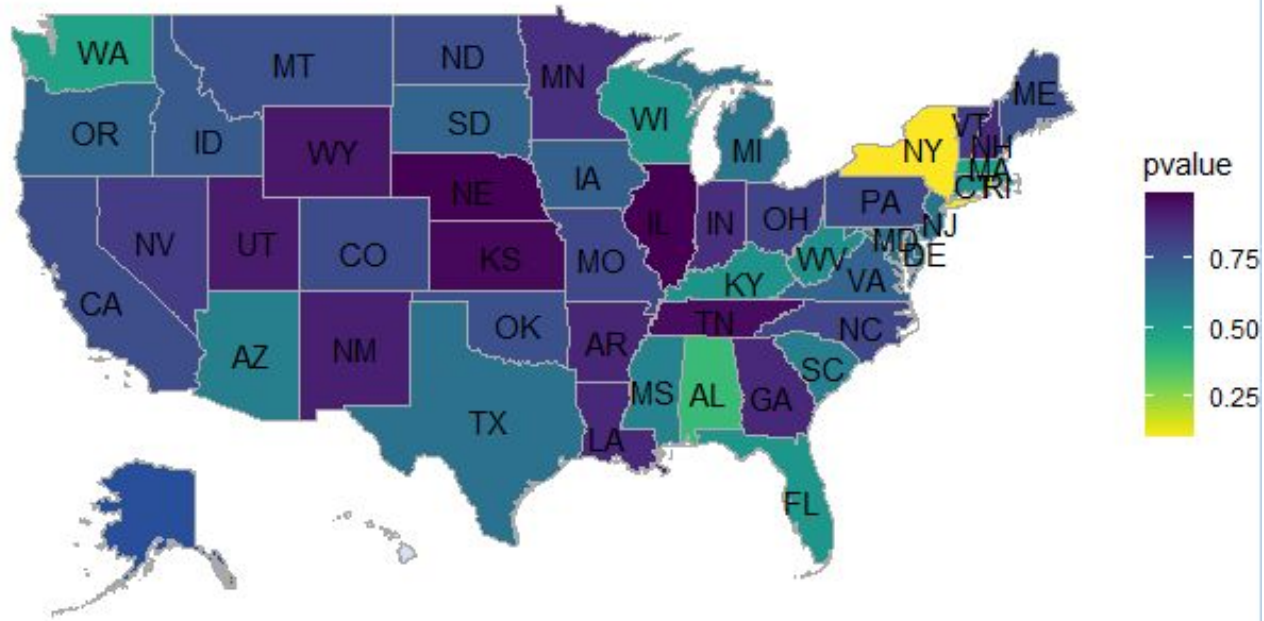
Residuals:
    Min       1Q   Median       3Q      Max
-7.8621 -2.6600 -0.8187  2.5962  9.1913

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept)  4.2674    0.3041   14.031 <2e-16 ***
yr           0.5054    0.3057    1.653  0.1
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 3.675 on 144 degrees of freedom
(1 observation deleted due to missingness)
Multiple R-squared:  0.01863,    Adjusted R-squared:  0.01181
F-statistic: 2.734 on 1 and 144 DF,  p-value: 0.1004
```

# Bias consistent over time?

Bias change over time/election



# Conclusion

- Spatiotemporal model shows systematic polling bias is constant over state and election
- Spatiotemporal model shows that percent Caucasian & previous election are significantly associated with the polling bias over space and time.
- Separate spatial models show percent Caucasian has an effect to the bias for all 3 elections, while previous election has effects to the bias for 2012 and 2016 elections. Percent agricultural land only has an effect in 2016 election.
- Largest bias over 3 elections is in New York. Polls failed to capture GOP support for New York in 2020 (~ +8%).
- There are spatial effects of bias for each election, however, they are not strong ( $\rho \sim 0.37$ ):
- Average positive bias across all years. The polls surveyed poorly and failed to capture Republican voters. More people voted for Republican than polls anticipated.
- The polls underestimated GOP supporters in general.
- Sampled surveys did not reflect GOP supports.



*Thanks for your attention!*